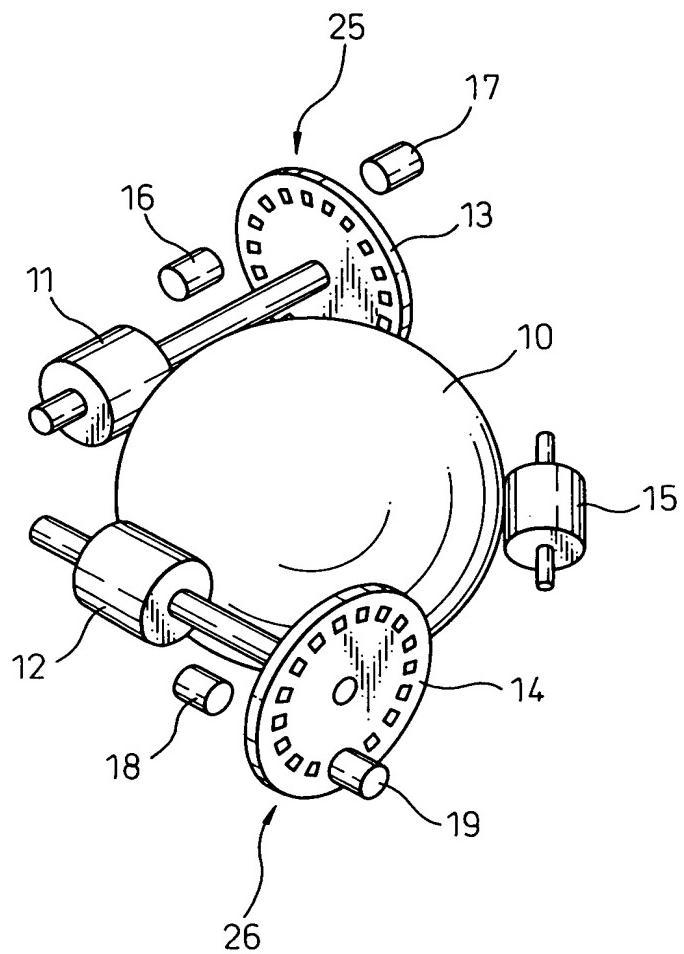


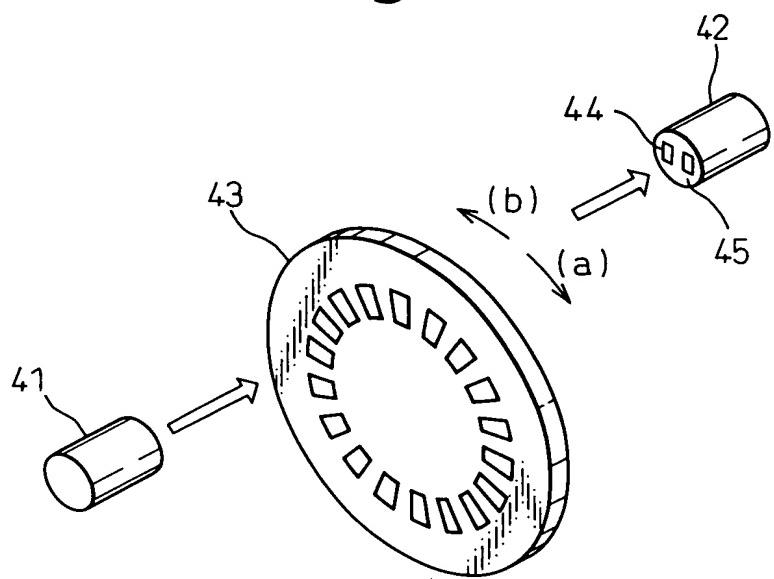
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Fig. 1



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Fig. 2



$\frac{3}{16}$

Fig. 3A

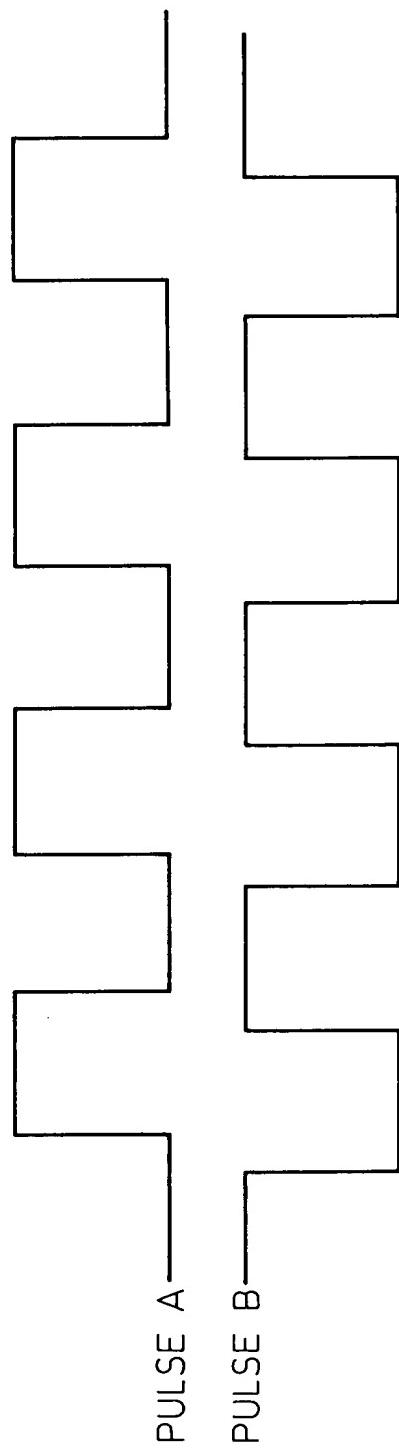
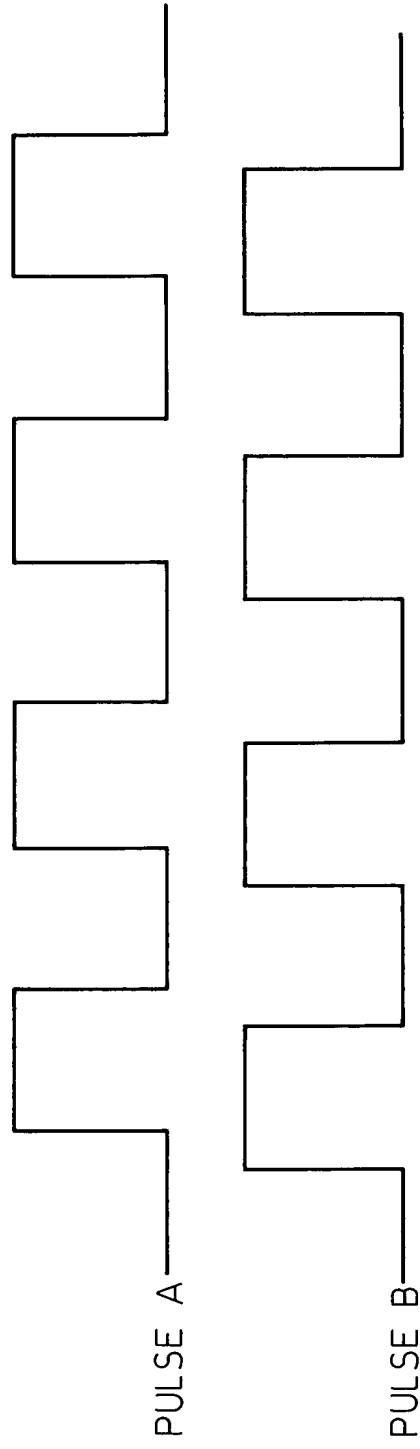


Fig. 3B



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Fig. 4A

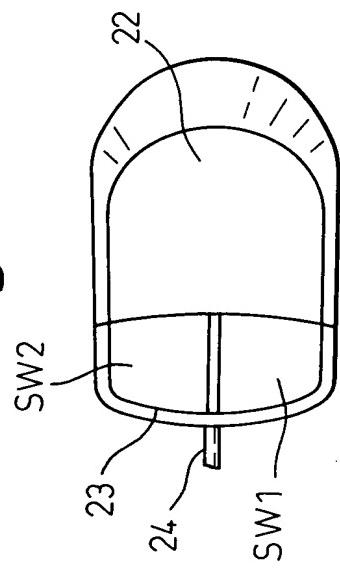


Fig. 4C

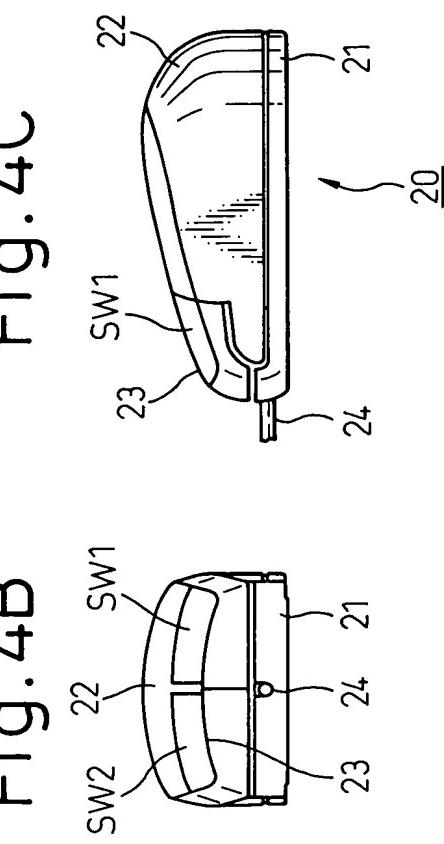


Fig. 4D

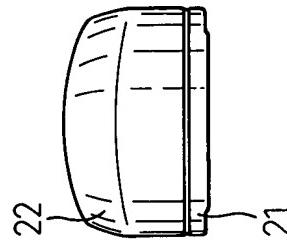
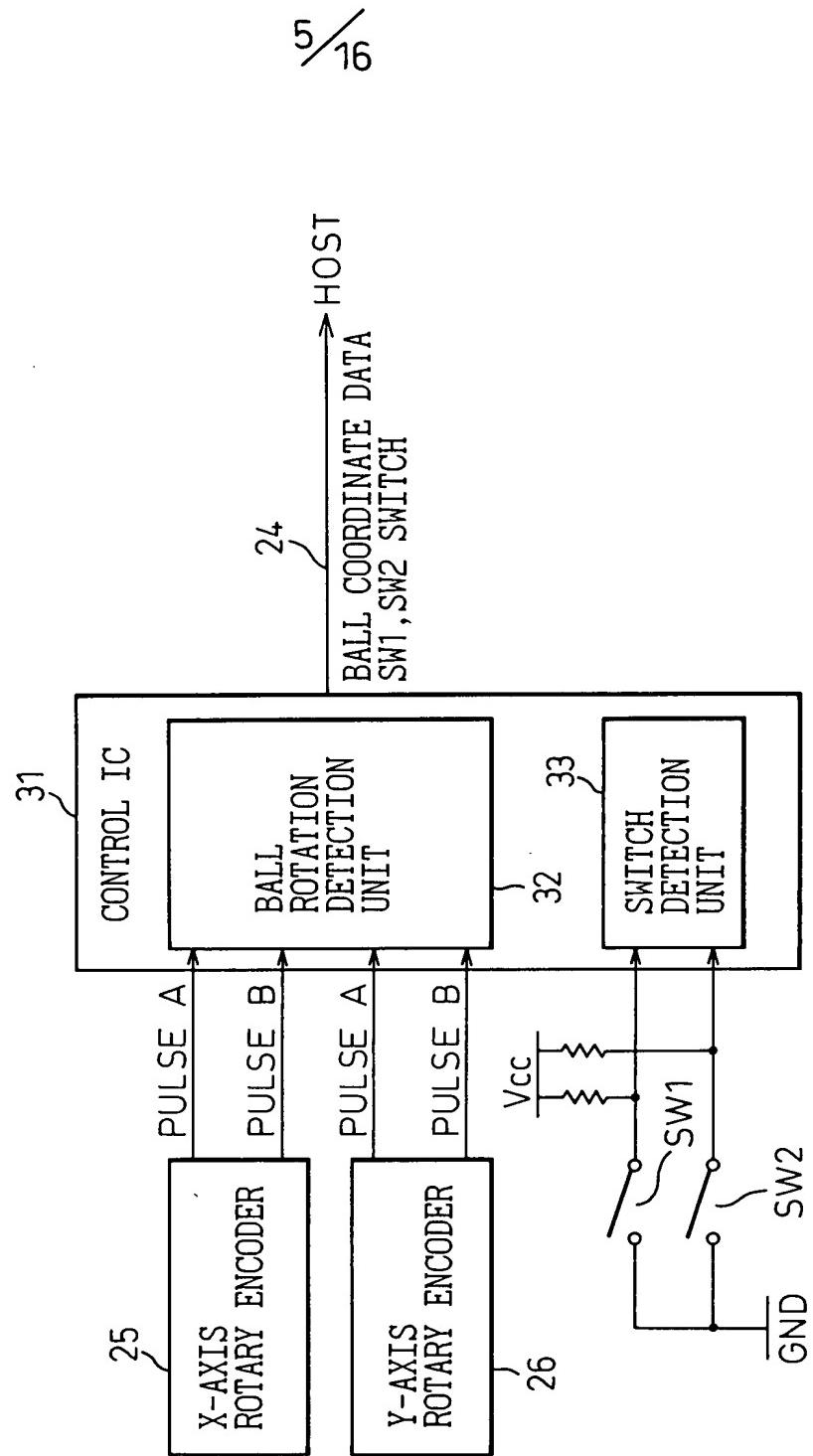


Fig. 5



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Fig. 6A

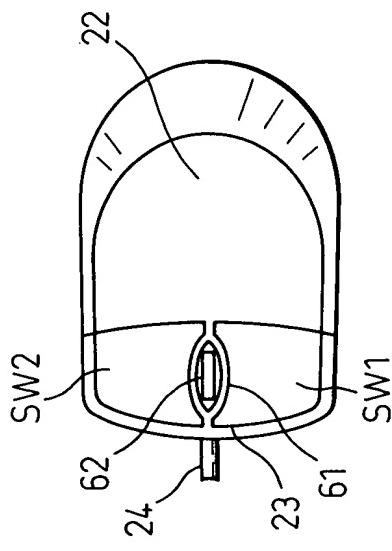


Fig. 6C

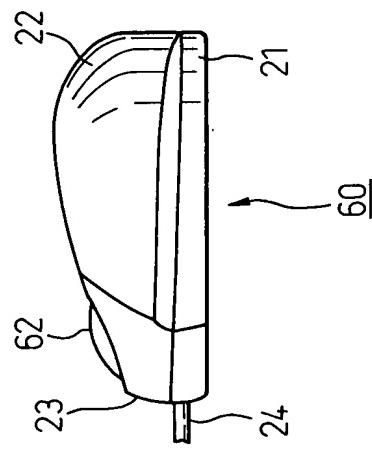


Fig. 6D

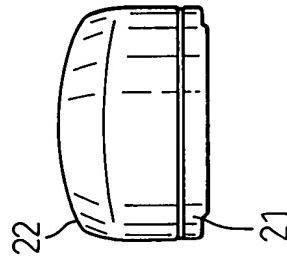
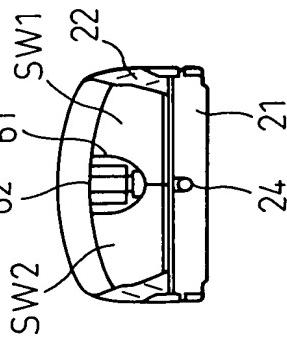
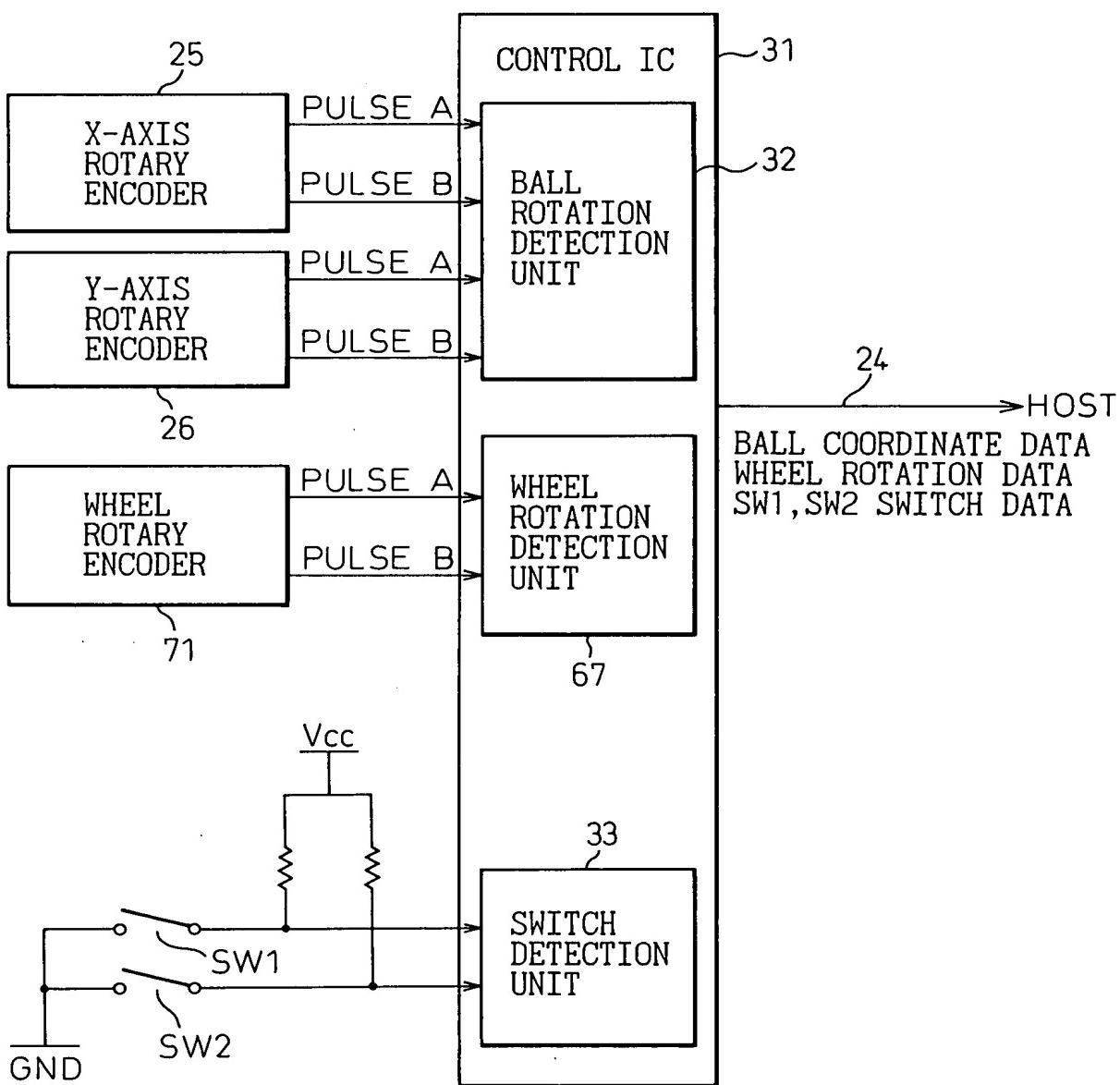


Fig. 6B



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Fig. 7



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Fig. 8

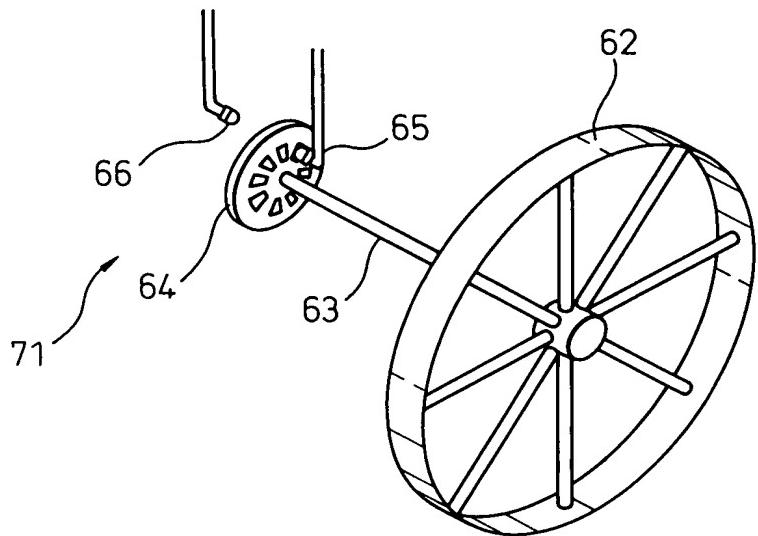
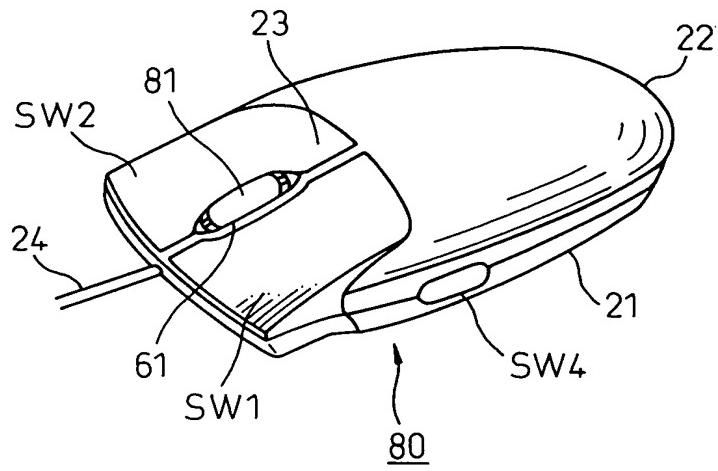


Fig. 9



$\frac{9}{16}$

Fig. 10A

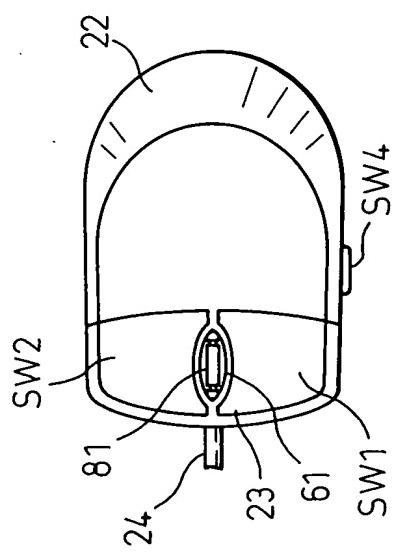


Fig. 10C

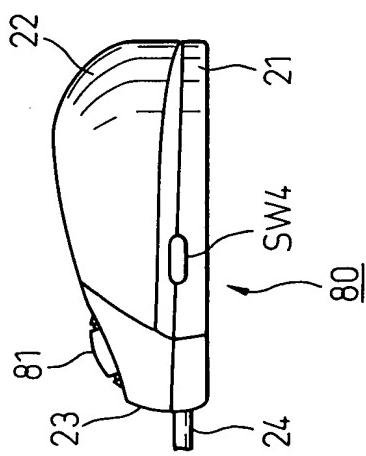


Fig. 10B

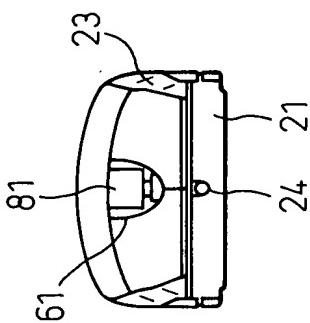


Fig. 10D

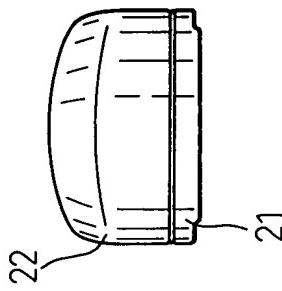
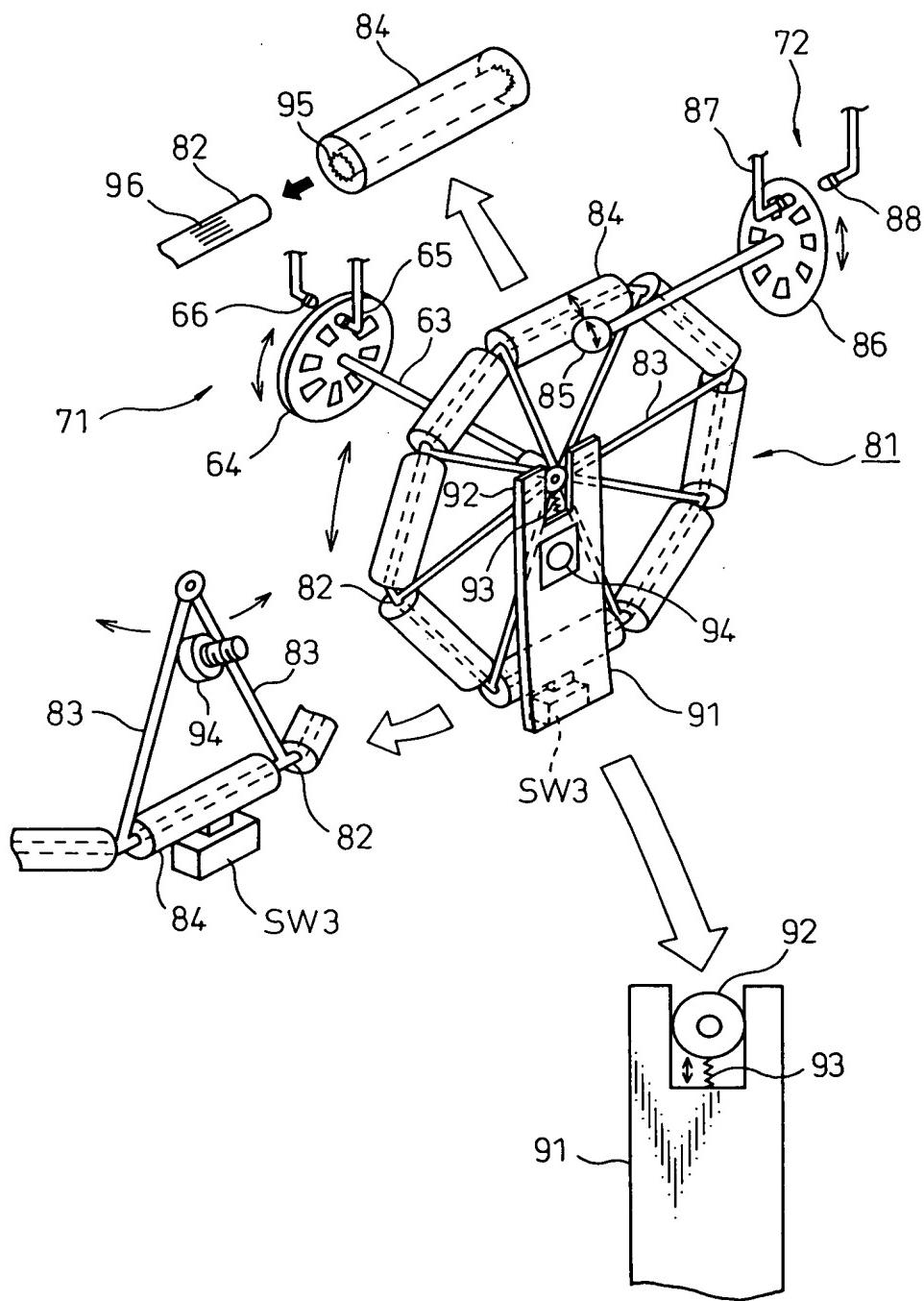
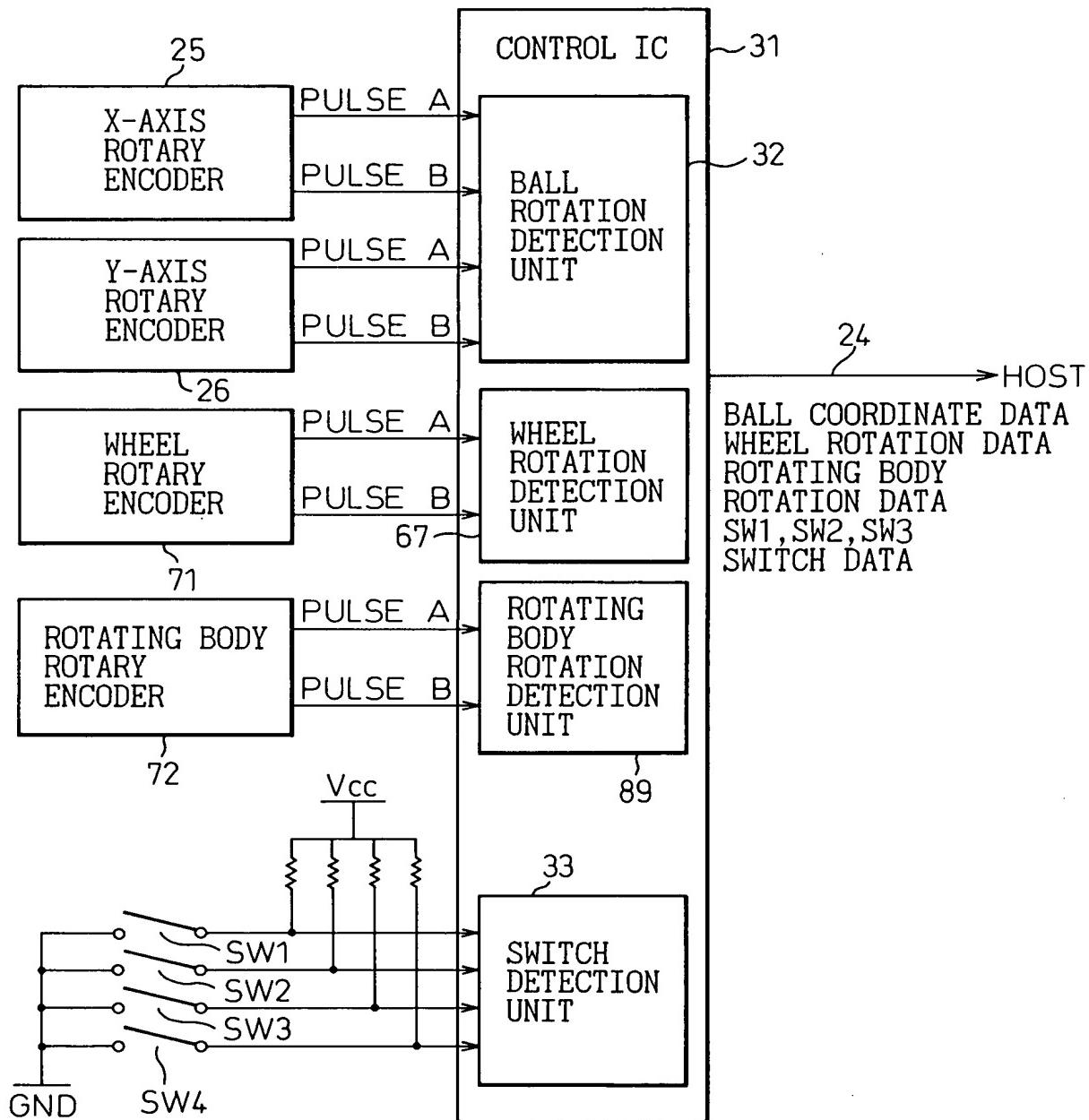


Fig. 11



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Fig. 12



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Fig. 13A
Fig. 13B
Fig. 13C

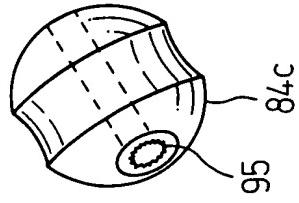
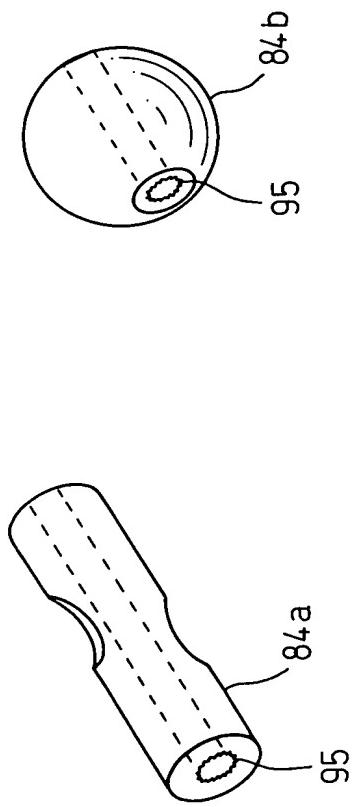


Fig. 14

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	FIRST BYTE	SECOND BYTE	THIRD BYTE	FOURTH BYTE	FIFTH BYTE
SW4 OFF NORMAL OUTPUT DATA	SW1, SW2, SW3 SWITCH DATA	BALL X-DIRECTION ROTATION DATA	BALL Y-DIRECTION ROTATION ENCODER	ROTATING BODY ROTATION DATA	WHEEL ROTATION DATA
SW4 ON OUTPUT DATA WITH SW4 BEING DEPRESSED	SW1, SW2, SW3 SWITCH DATA	ROTATING BODY ROTATION DATA	WHEEL ROTATION DATA	0	0

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Fig. 15

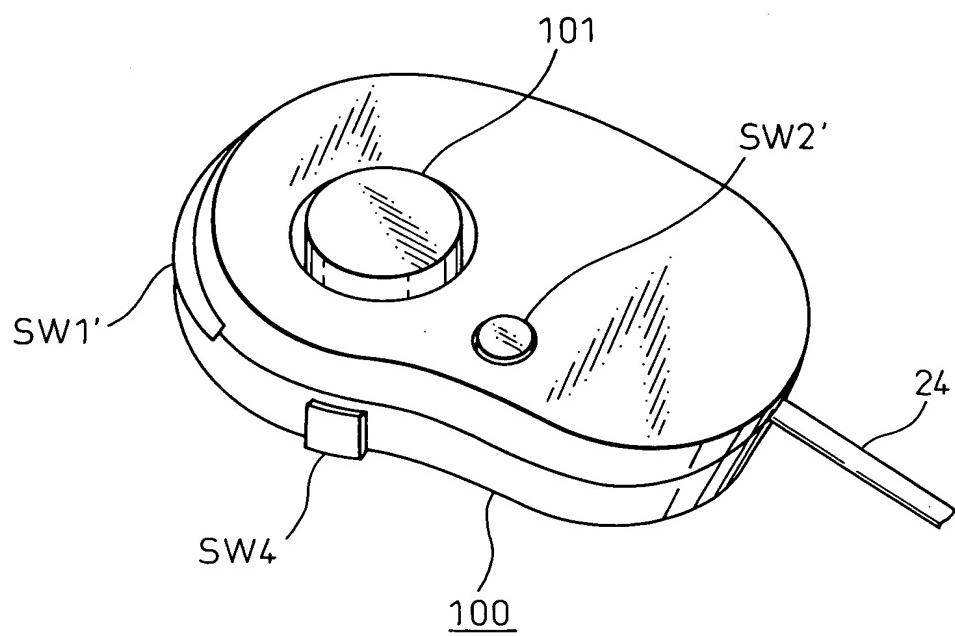


Fig. 16

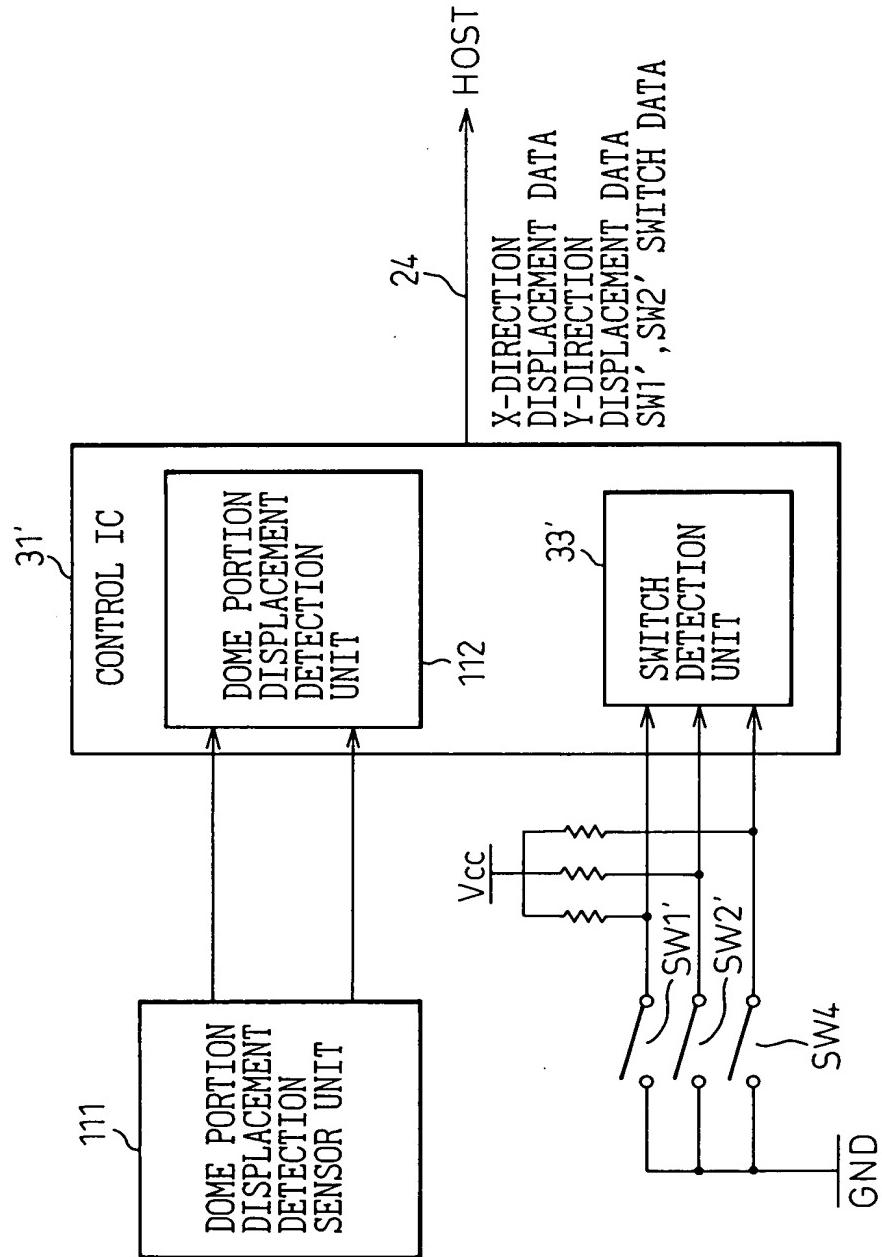


Fig. 17

